

Init

```
Needs["CCompilerDriver`"]

SetDirectory[NotebookDirectory[]];

libraryPath = CreateLibrary[
  {"cfiles/link.c",
   "cfiles/boids.c"}, 
  "boids",
  "IncludeDirectories" → {Directory[] <> "/cfiles"}];
Print[libraryPath]

/Users/christopher/Library/Mathematica/SystemFiles/LibraryResources/MacOSX-x86-64/boids.
dylib

runBoids = LibraryFunctionLoad[libraryPath, "runBoids", {Integer(*step count*),
  Integer(*steps to return count*), {Real, 2}(*initial positions*),
  {Real, 2}(*initial velocities*), {Real, 2}(*parameters*), {Real, 3}}]
```

LibraryFunction[ Function name: runBoids] Argument count: 5

Without Predators

```
initPos = RandomReal[{-1, 1}, {100, 1}];
initVel = RandomReal[{-1, 1}, {100, 1}];
parameters =
  Table[{10(*alignment*), 1(*seperation*), 1(*cohesion*), 0(*species*),
    1(*mass*), 0.3(*visibility radius*), 0.01(*max velocity*), 0.001
    (*max acceleration*), 0.025(*seperation radius*), 1.0(*fear*),
    0(*predator frames*), 10(*frames to death*)}, {100}];

initPos = RandomReal[{-1, 1}, {1000, 2}];
initVel = RandomReal[{-1, 1}, {1000, 2}];
parameters =
  Table[{10(*alignment*), 1(*seperation*), 1(*cohesion*), 0(*species*),
    1(*mass*), 0.3(*visibility radius*), 0.01(*max velocity*), 0.001
    (*max acceleration*), 0.025(*seperation radius*), 1.0(*fear*),
    0(*predator frames*), 10(*frames to death*)}, {1000}];
```

```

initPos = RandomReal[{-1, 1}, {1000, 2}];
initVel = RandomReal[{-1, 1}, {1000, 2}];
parameters =
  Table[{10(*alignment*), 1(*seperation*), 10(*cohesion*), 0(*species*),
    1(*mass*), 0.3(*visibility radius*), 0.01(*max velocity*), 0.001
    (*max acceleration*), 0.025(*seperation radius*), 1.0(*fear*),
    0(*predator frames*), 10(*frames to death*)}, {1000}];
steps = runBoids[1000, 1000, initPos, initVel, parameters];
AbsoluteTiming[runBoids[1000, 2, initPos, initVel, parameters];]
{0.089834, Null}

0.079085`*(100^3)/60/60/4
5.49201

7.34016`

10^3*10/60/60//N
2.77778

10.706806`

center = Mean[Catenate[steps]];
distances = EuclideanDistance[center, #] & /@ Catenate[steps];
Histogram[distances]



Mean[distances]



0.461488



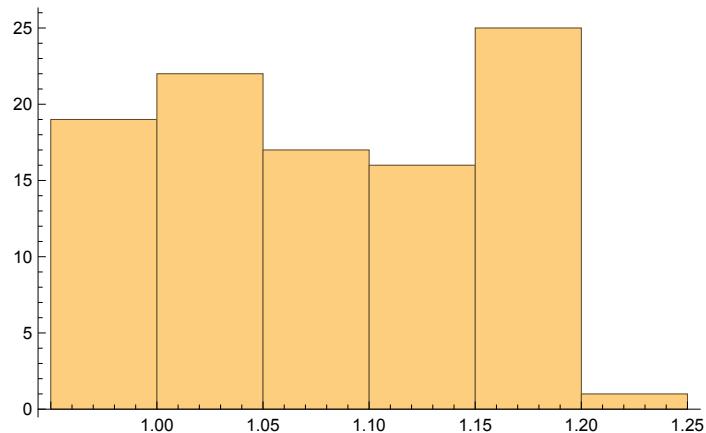
StandardDeviation[distances]



0.097804


```

```
Histogram[Norm /@ (Subtract @@ Reverse@steps[[-2 ;;]])]
```

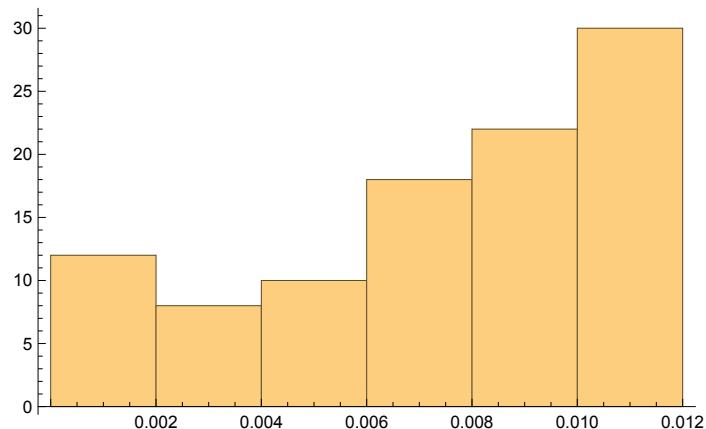


A reasonable measure of something:

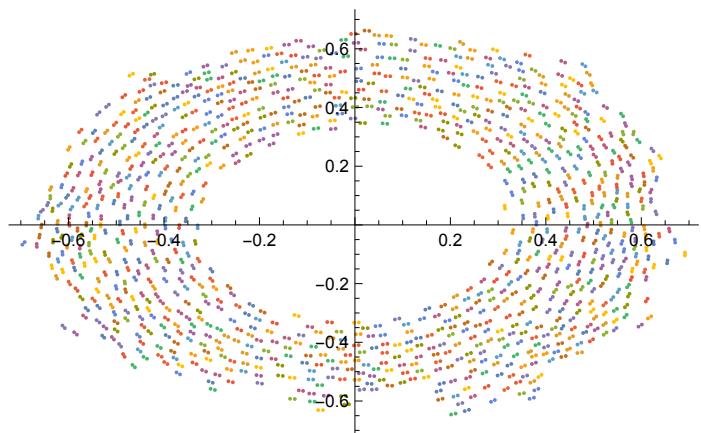
```
Mean[Norm /@ (Subtract @@ steps[[All, -2 ;;]])]
```

```
0.00566809
```

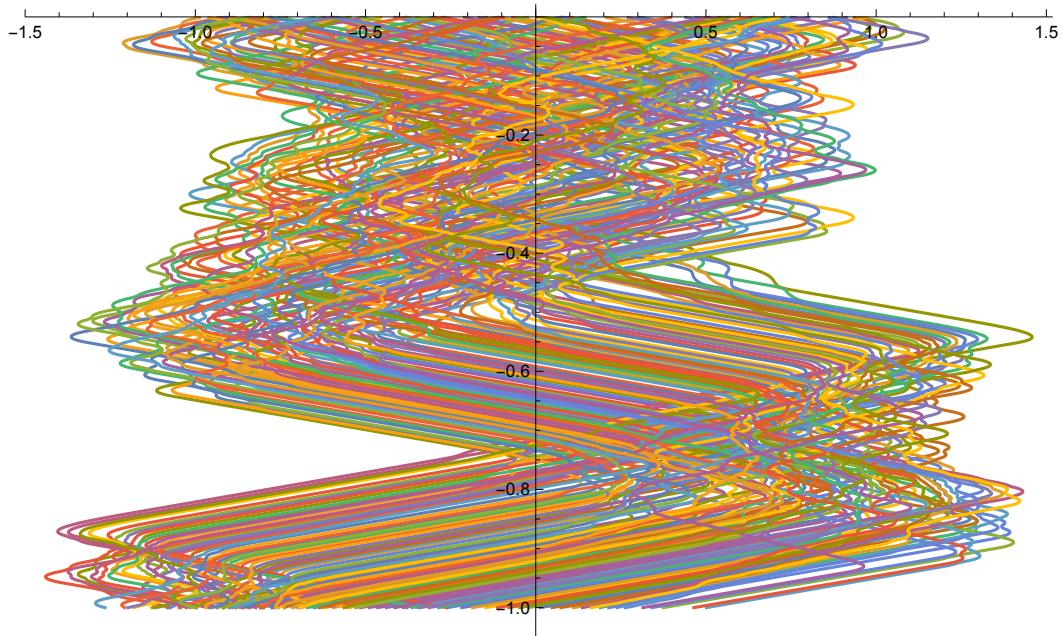
```
Histogram[Norm /@ (Subtract @@ steps[[All, -2 ;;]])]
```



```
ListPlot@steps[[All, -2 ;;]]
```



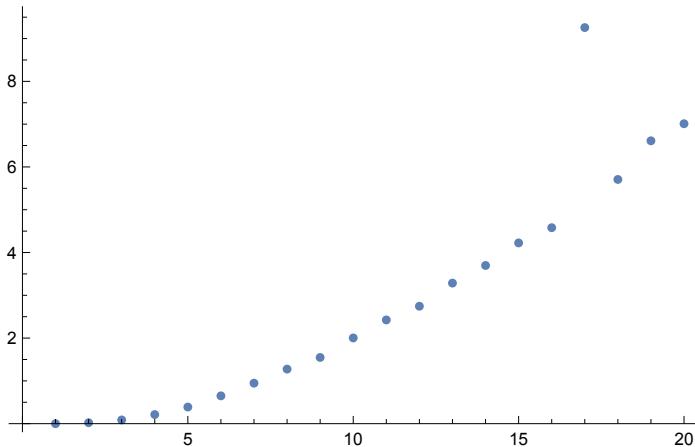
```
ListLinePlot[MapIndexed[{#1, -First[#2]/1000} &, #] & /@ steps[[All, All, 1]],
PlotRange -> {Automatic, All}]
```



Phase Diagram

```
times = Table[Module[{initPos, initVel, parameters},
  initPos = RandomReal[{-1, 1}, {n, 2}];
  initVel = RandomReal[{-1, 1}, {n, 2}];
  parameters =
    Table[{10(*alignment*), 1(*seperation*), 1(*cohesion*), 0(*species*),
      1(*mass*), 0.3(*visibility radius*), 0.01(*max velocity*),
      0.001(*max acceleration*), 0.025(*seperation radius*), 1.0
      (*fear*), 0(*predator frames*), 10(*frames to death*)}, {n}];
  AbsoluteTiming[runBoids[1000, 2, initPos, initVel, parameters]][[1]]
], {n, 1, 1000, 50}]
{0.000273, 0.022402, 0.086847, 0.212882, 0.388209, 0.649892,
 0.946567, 1.27527, 1.54806, 2.00375, 2.4247, 2.74454, 3.28513,
 3.69716, 4.22439, 4.57997, 9.25714, 5.70732, 6.61105, 7.00996}
```

```
ListPlot[times]
```



```
if = Interpolation[Transpose[{Range[1, 1000, 50], times}]]
```

InterpolatingFunction[Domain: {{1., 951.}} Output: scalar]

```
100^3 * if[200] / 3 / 60 / 60
```

36.6844

```
Dimensions[steps2]
```

{200, 1000, 2}

```
Transpose[steps2][[-500 ;;]]
```

```
{ {{-1.05837, -0.789296}, {-0.24979, -0.0763523}, {2.79794, -0.251807},  
{1.59536, 0.474895}, {-0.668717, 0.474544}, {3.319, -0.526554},  
{-0.817533, -0.88365}, {-0.0897784, 0.336451}, ... 184 ... ,  
{1.59199, 0.0797473}, {3.33536, -0.48146}, {-0.565913, 0.0760649},  
{-1.1367, -0.881877}, {3.29441, -0.380596}, {-0.932509, -0.784458},  
{3.28443, -0.501919}, {1.31412, 0.396489} }, ... 498 ... , { ... 1 ... } }
```

large output

show less

show more

show all

set size limit...

```
{Mean[#], Median[#], StandardDeviation[#]} & /@
```

```
Map[Norm, Subtract @@ Partition[Transpose[steps2][[-500 ;;]], 2, 1], {2}]
```

```

ListPlot[
 Mean /@ Map[Norm, Subtract @@ Partition[Transpose[steps2][[-500 ;;]], 2, 1], {2}]]
```

```

Dimensions[Subtract @@ Partition[Transpose[steps2][[-500 ;;]], 2, 1]]
{499, 200, 2}

Dimensions[steps2[[All, -500 ;;]]]
{200, 500, 2}

Space3:

LaunchKernels[6]
{KernelObject[1, local], KernelObject[2, local], KernelObject[3, local],
 KernelObject[4, local], KernelObject[5, local], KernelObject[6, local]}

Now + 16.3764245` min
```

Thu 21 Sep 2017 11:28:20 GMT-7.

```

space3 = ParallelTable[Module[{initPos, initVel, parameters, steps, norms, n, s},
  s = 1;
  n = 200;
  initPos = RandomReal[{-1, 1}, {n, 2}];
  initVel = RandomReal[{-1, 1}, {n, 2}];
  parameters =
    Table[{a(*alignment*), s(*seperation*), c(*cohesion*), 0(*species*),
      1(*mass*), 0.3(*visibility radius*), 0.01(*max velocity*),
      0.001(*max acceleration*), 0.025(*seperation radius*), 1.0
      (*fear*), 0(*predator frames*), 10(*frames to death*}), {n}];
  steps = runBoids[1000, 500, initPos, initVel, parameters];
  norms = Map[Norm, Subtract @@@ Partition[Transpose[steps], 2, 1], {2}];
  {Mean[#], Median[#], StandardDeviation[#]} & /@ norms
],
{c, 0, 10, 10/100},
{a, 1, 21, 20/100}];
```

Now

 Thu 21 Sep 2017 11:32:18 GMT-7.

Space4:

```

space4 =
  ParallelTable[Module[{initPos, initVel, parameters, steps, norms, n, s}, s = 1;
  n = 200;
  initPos = RandomReal[{-1, 1}, {n, 2}];
  initVel = RandomReal[{-1, 1}, {n, 2}];
  parameters =
    Table[{a(*alignment*), s(*seperation*), c(*cohesion*), 0(*species*),
      1(*mass*), 0.3(*visibility radius*), 0.01(*max velocity*),
      0.001(*max acceleration*), 0.025(*seperation radius*), 1.0
      (*fear*), 0(*predator frames*), 10(*frames to death*}), {n}];
  steps = runBoids[1000, 500, initPos, initVel, parameters];
  norms = Map[Norm, Subtract @@@ Partition[Transpose[steps], 2, 1], {2}];
  {Mean[#], Median[#], StandardDeviation[#]} & /@ norms],
{c, 0, 10, 10/100},
{a, 1, 21, 20/100},
100];
```

Space:

```

Table[Module[{initPos, initVel, parameters, steps, norms, n},
  n = 200;
  initPos = RandomReal[{-1, 1}, {n, 2}];
  initVel = RandomReal[{-1, 1}, {n, 2}];
  parameters =
    Table[{a(*alignment*), s(*seperation*), c(*cohesion*), 0(*species*),
      1(*mass*), 0.3(*visibility radius*), 0.01(*max velocity*), 0.001
      (*max acceleration*), 0.025(*seperation radius*), 1.0(*fear*),
      0(*predator frames*), 10(*frames to death*)}, {n}];
  steps = runBoids[1000, 2, initPos, initVel, parameters];
  norms = Norm /@ (Subtract @@ steps[[All, -2 ;]]);
  {Mean[norms], Median[norms], StandardDeviation[norms]}
],
{c, 0, 10, 10/100},
{a, 1, 21, 20/100},
{s, 1, 11, 10/100}]
$Aborted

```

Space2:

```

Table[Module[{initPos, initVel, parameters, steps, norms, n},
  n = 200;
  initPos = RandomReal[{-1, 1}, {n, 2}];
  initVel = RandomReal[{-1, 1}, {n, 2}];
  parameters =
    Table[{a(*alignment*), s(*seperation*), c(*cohesion*), 0(*species*),
      1(*mass*), 0.3(*visibility radius*), 0.01(*max velocity*), 0.001
      (*max acceleration*), 0.025(*seperation radius*), 1.0(*fear*),
      0(*predator frames*), 10(*frames to death*)}, {n}];
  steps = runBoids[1000, 2, initPos, initVel, parameters];
  norms = Norm /@ (Subtract @@ steps[[All, -2 ;]]);
  {Mean[norms], Median[norms], StandardDeviation[norms]}
],
{c, 0, 40, 40/100},
{a, 1, 71, 70/100},
{s, 1, 51, 50/100}]
$Aborted

```

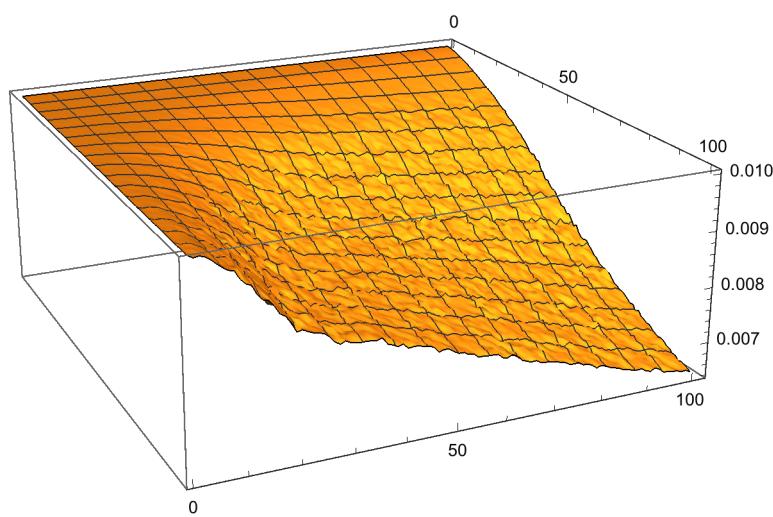
Will finish at 5:30am on Tuesday the 19th

```
Norm/@ (Subtract@@@steps[[All, -2 ;;]])  
{0.01, 0.01, 0.01, 0.00987525, 0.01, 0.01, 0.01, 0.01, 0.01, 0.01, 0.01, 0.01,  
0.01, 0.01, 0.01, 0.01, 0.01, 0.01, 0.01, 0.01, 0.01, 0.01, 0.01, 0.01, 0.01,  
0.01, 0.01, 0.00865782, 0.01, 0.01, 0.01, 0.01, 0.01, 0.01, 0.01, 0.01, 0.01,  
0.01, 0.01, 0.00911974, 0.01, 0.01, 0.01, 0.01, 0.01, 0.01, 0.01, 0.01, 0.01, 0.01,  
0.01, 0.01, 0.01, 0.01, 0.01, 0.01, 0.01, 0.01, 0.01, 0.01, 0.01, 0.01, 0.01,  
0.01, 0.01, 0.01, 0.01, 0.01, 0.01, 0.01, 0.01, 0.01, 0.01, 0.01, 0.01, 0.01,  
0.01, 0.01, 0.01, 0.01, 0.01, 0.01, 0.01, 0.01, 0.01, 0.01, 0.01, 0.01, 0.01, 0.01,  
0.01, 0.01, 0.01, 0.01, 0.01, 0.01, 0.01, 0.01, 0.01, 0.01, 0.01, 0.01, 0.01, 0.01, 0.01,  
0.01, 0.01, 0.01, 0.01, 0.01, 0.01, 0.01, 0.01, 0.01, 0.01, 0.01, 0.01, 0.01, 0.01, 0.01}  
  
space = Get[FileNameJoin[{NotebookDirectory[], "space.wl"}]];  
space2 = Get[FileNameJoin[{NotebookDirectory[], "space2.wl"}]];  
space3 = Get[FileNameJoin[{NotebookDirectory[], "space3.wl"}]];  
Get[FileNameJoin[{NotebookDirectory[], "space4.mx"}]];  
  
Dimensions[space]  
{101, 101, 101, 3}  
  
Dimensions[space3]  
{101, 101, 499, 3}  
  
means = Map[Mean, space4[[All, All, All, All, 1]], {2, 3}];
```

`ImageAdjust@Image@means`



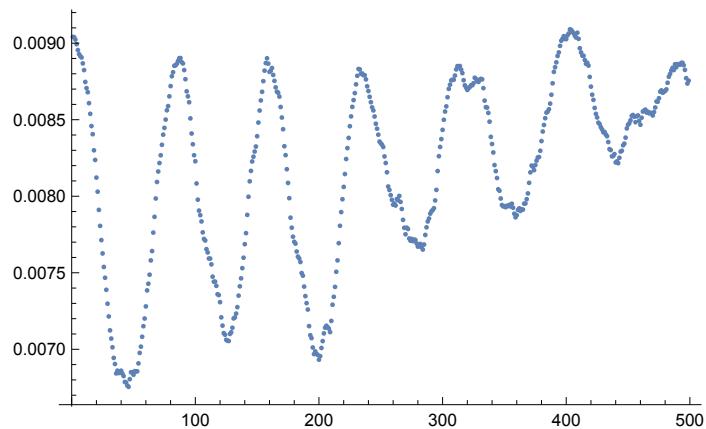
`ListPlot3D[means]`



```
ListAnimate[Table[
  ImageAdjust@Image[Map[Mean, space4[[All, All, n, All, 1]], {2}], ImageSize -> 400],
  {n, 1, 100, 1}], AnimationRunning -> False]
```



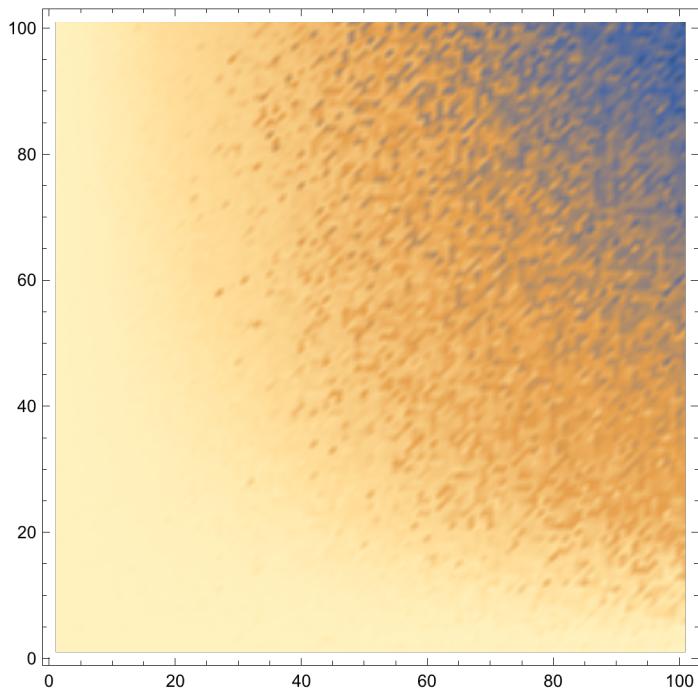
```
ListPlot@space3[[100, 52, All, 1]]
```



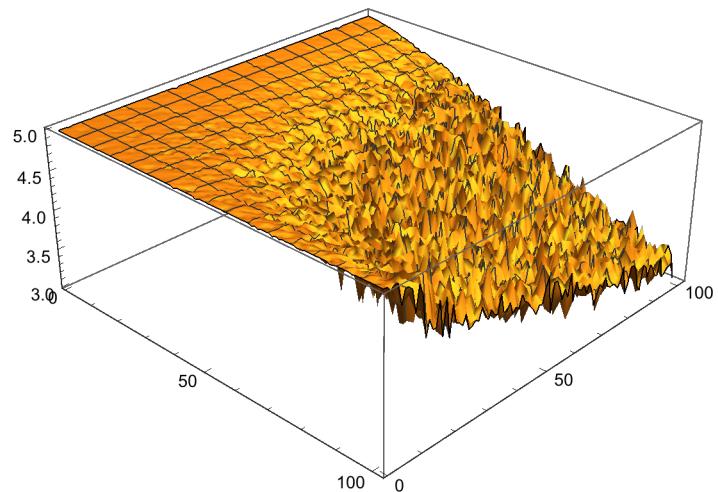
```
ListAnimate[Table[ImageAdjust@Image[space3[[All, All, n, 1]], ImageSize -> 400], {n, 1, 499, 1}], AnimationRunning -> False]
```



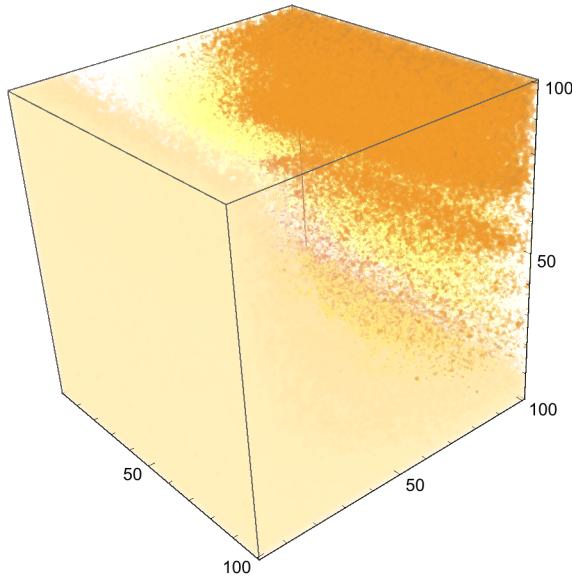
```
ListDensityPlot@Map[Total, space3[[All, All, All, 1]], {2}]
```



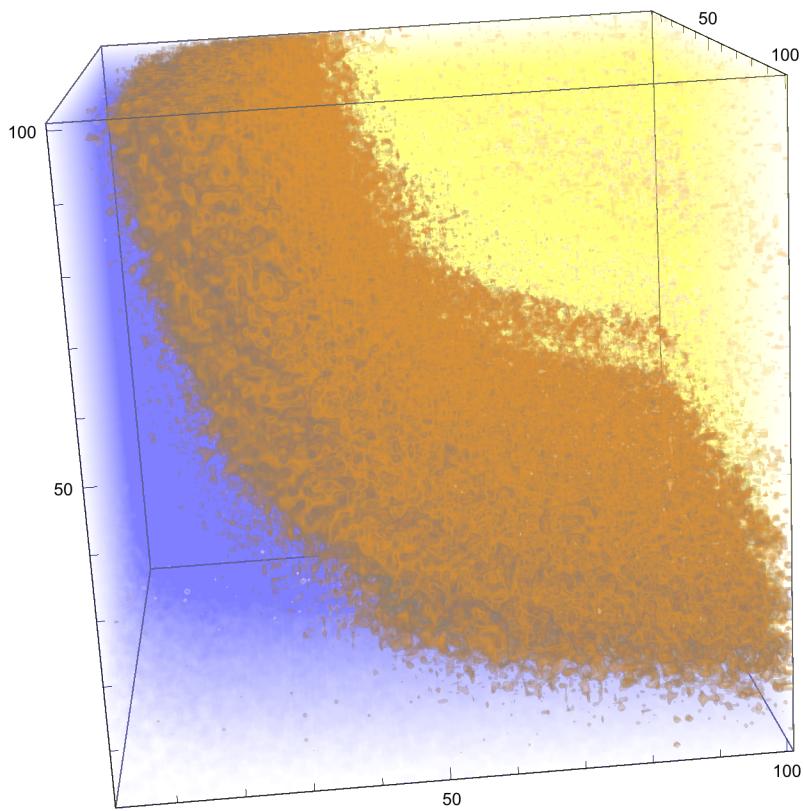
```
ListPlot3D[Map[Total, space3[[All, All, All, 1]], {2}]]
```



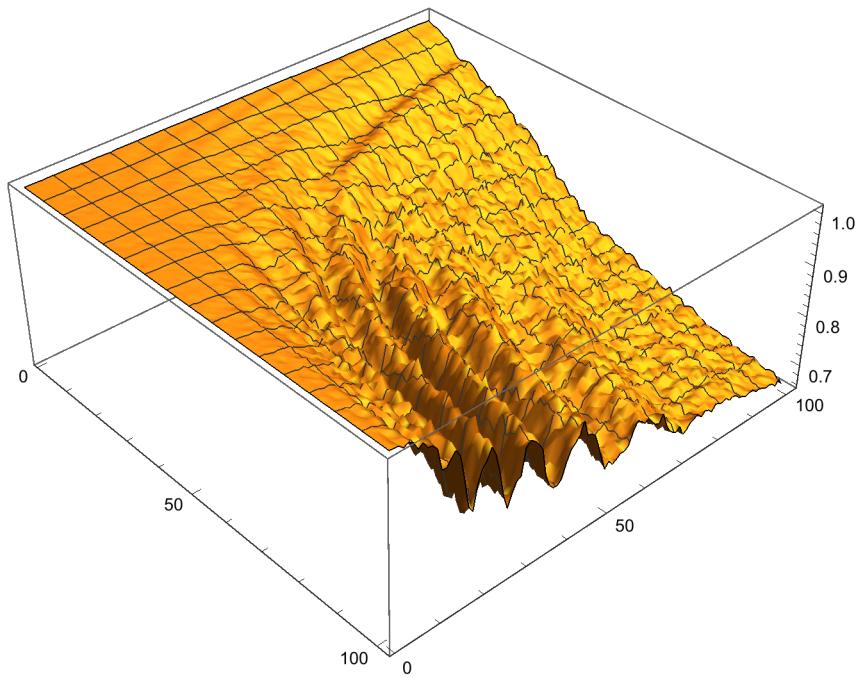
ListDensityPlot3D@space[[All, All, All, 1]]



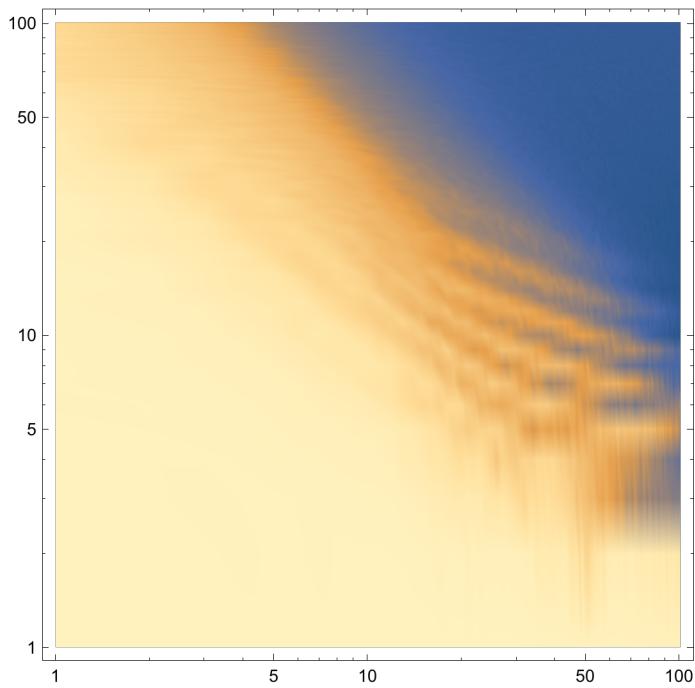
ListDensityPlot3D@space[[All, All, All, 3]]



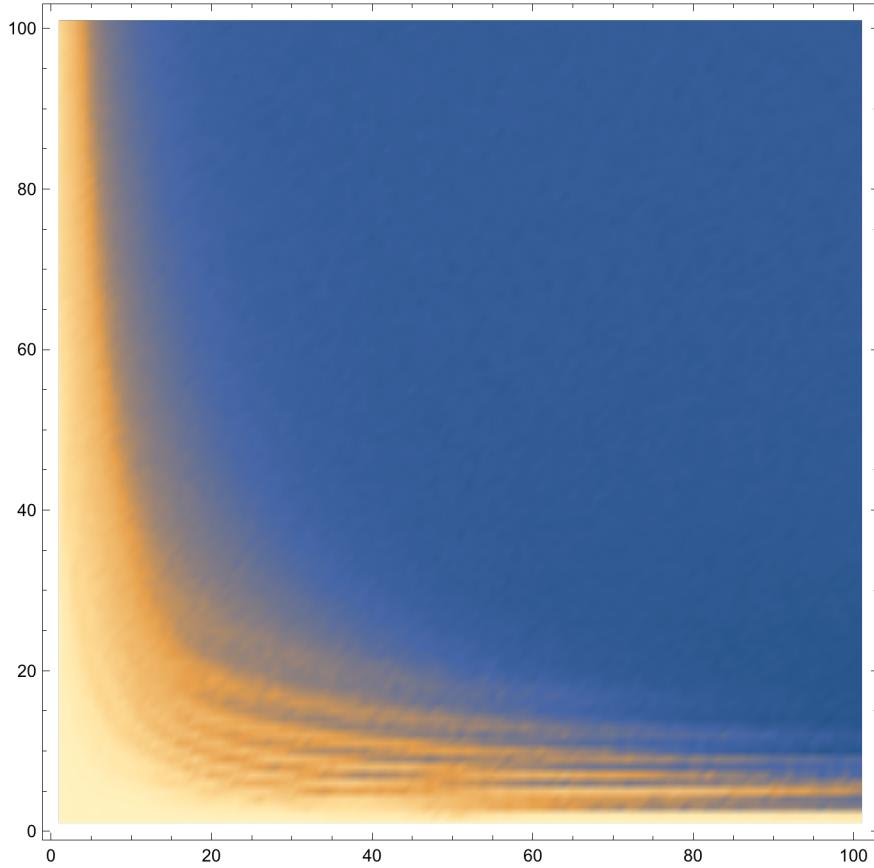
```
ListPlot3D[Map[Total, space[[All, All, All, 1]], {2}]]
```



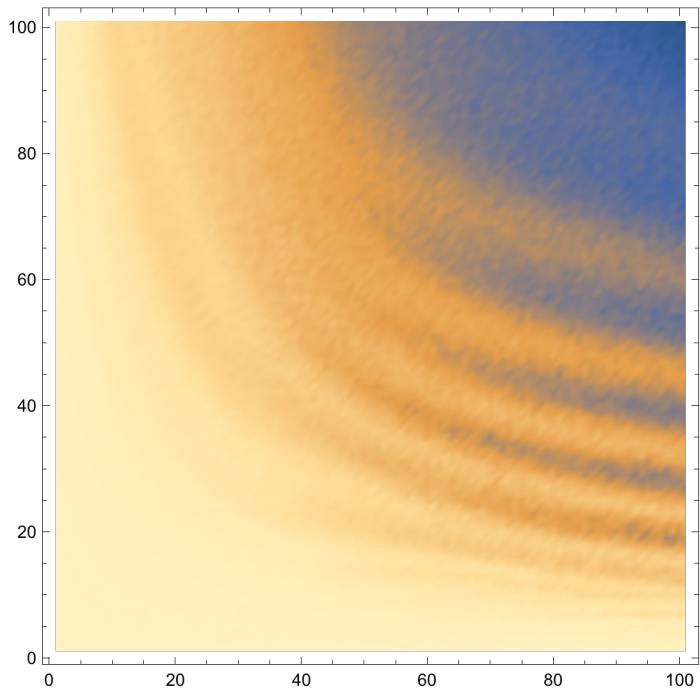
```
ListDensityPlot[Map[Total, space2[[All, All, All, 1]], {2}],  
ScalingFunctions -> {"Log", "Log"}]
```



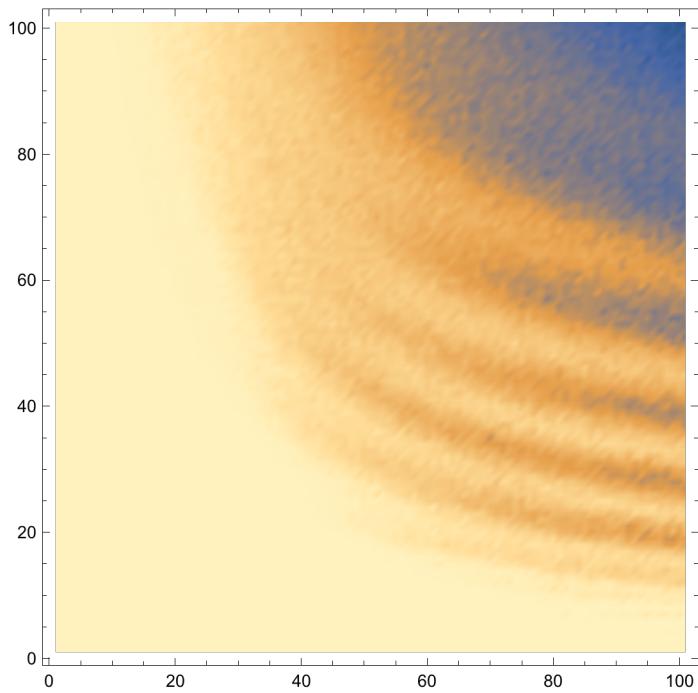
```
ListDensityPlot[Map[Total, space2[[All, All, All, 1]], {2}]]
```



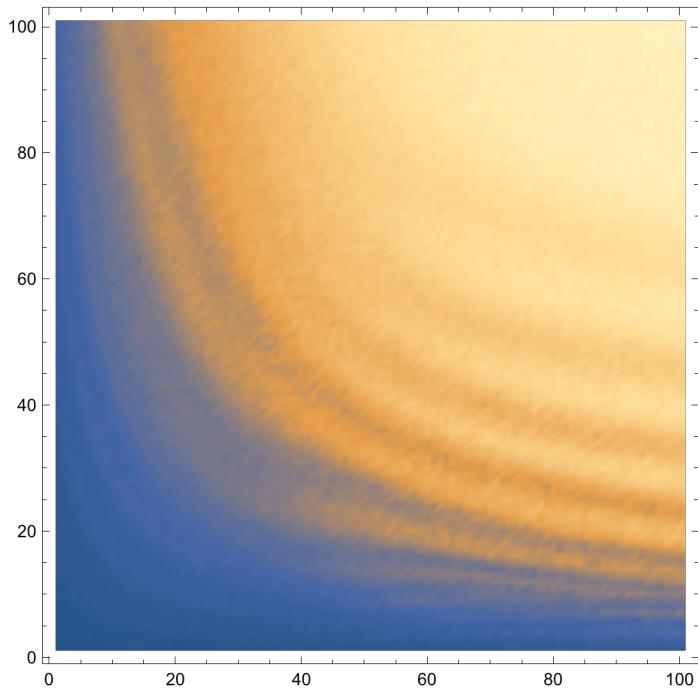
```
ListDensityPlot[Map[Total, space[[All, All, All, 1]], {2}]]
```

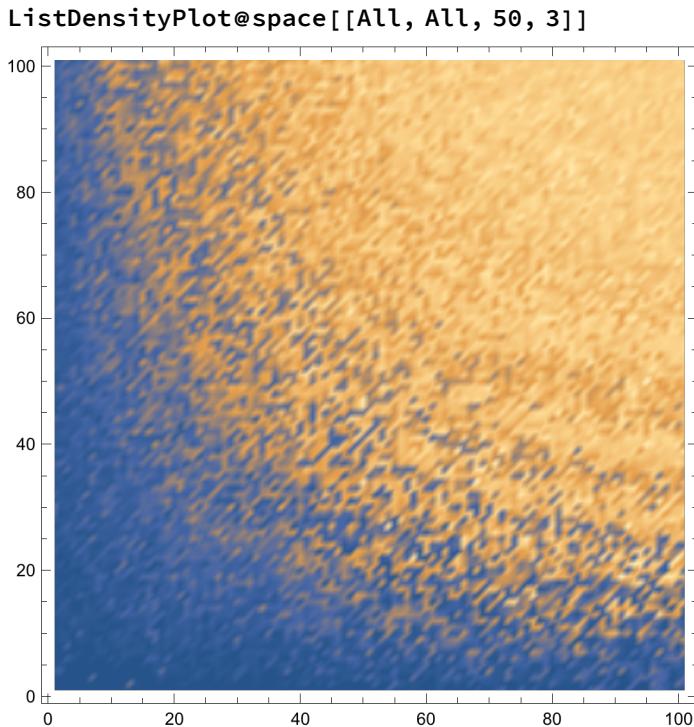


```
ListDensityPlot[Map[Total, space[[All, All, All, 2]], {2}]]
```



```
ListDensityPlot[Map[Total, space[[All, All, All, 3]], {2}]]
```





With Predators

Variable visibility radii:

```

initPos = RandomReal[{-1, 1}, {1000, 2}];
initVel = RandomReal[{-1, 1}, {1000, 2}];
parameters = Table[
  {10(*alignment*), 1(*seperation*), 1(*cohesion*), RandomChoice[{0, 1, 3, 4}]
   (*species*), 1(*mass*), RandomReal[{0.2, 0.5}](*visibility radius*), 0.01
   (*max velocity*), 0.001(*max acceleration*), 0.025(*seperation radius*),
   1.0(*fear*), 0(*predator frames*), 10(*frames to death*}, {1000}];

steps = runBoids[10000, 10000, initPos, initVel, parameters];
boidColors = ColorData["TemperatureMap"] /@ Rescale[parameters[[All, 6]]];
Manipulate[Graphics[MapThread[{#2, Point[#1]} &, {steps[[All, n]], boidColors}],
  PlotRange -> 2], {n, 1, Length@First@steps, 1}]

```

```

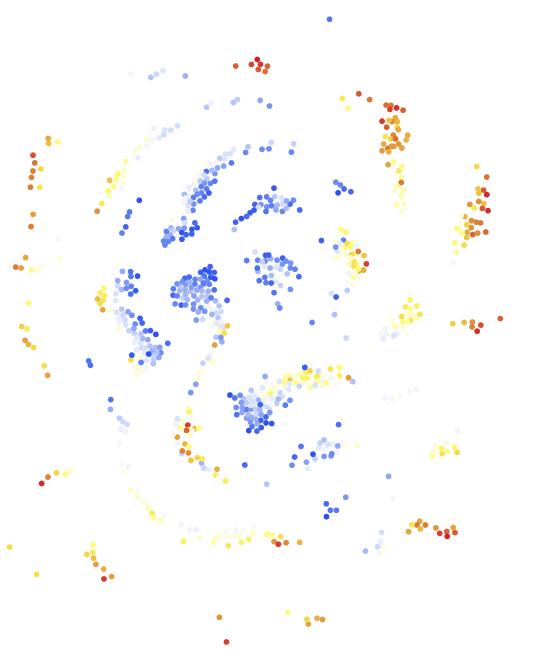
center = Mean[steps[[All, -1]]];
ListPlot[Transpose[{EuclideanDistance[center, #] & /@ steps[[All, -1]],
parameters[[All, 6]]}], PlotRange -> {{0, 3}, All}]

0.5
0.4
0.3
0.2
0.1
0.0
0.5 1.0 1.5 2.0 2.5 3.0

```

Manipulate[center = Mean[steps[[All, n]]];
ListPlot[Transpose[
{EuclideanDistance[center, #] & /@ steps[[All, n]], parameters[[All, 6]]}],
PlotRange -> {{0, 3}, All}], {n, 1, Length@First@steps, 1}]

Graphics[
MapThread[{#2, Point[#1]} &, {steps[[All, 10000]], boidColors}], PlotRange -> 2]



Persistent Homology